

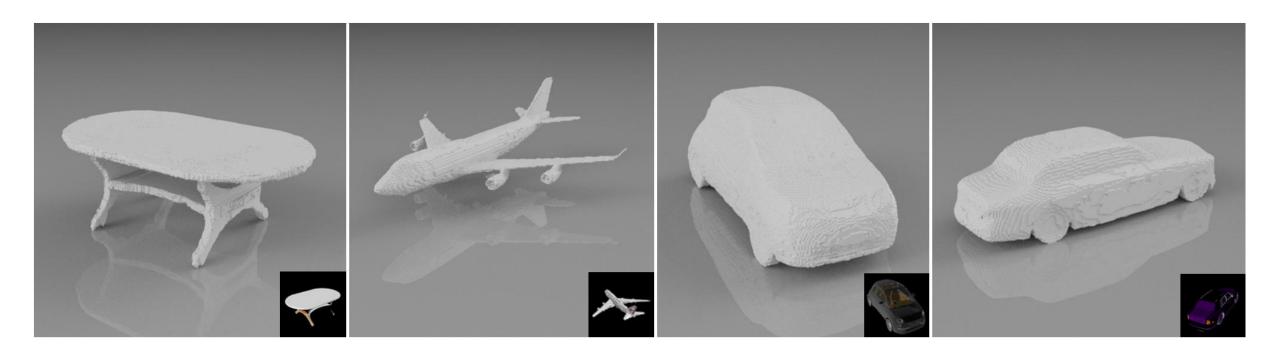
Matryoshka Networks:

Predicting 3D Geometry via Nested Shape Layers

Stephan R. Richter, Stefan Roth

Andrea Felicetti, Stefano Pini, Muhammad Shahid, Raffaele Vaira

Goal: 3D reconstruction of object shapes from 2D images

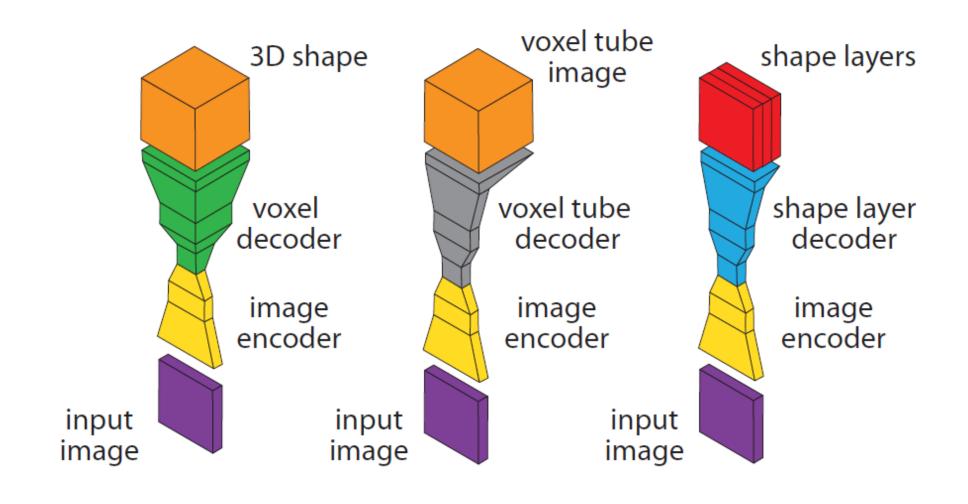




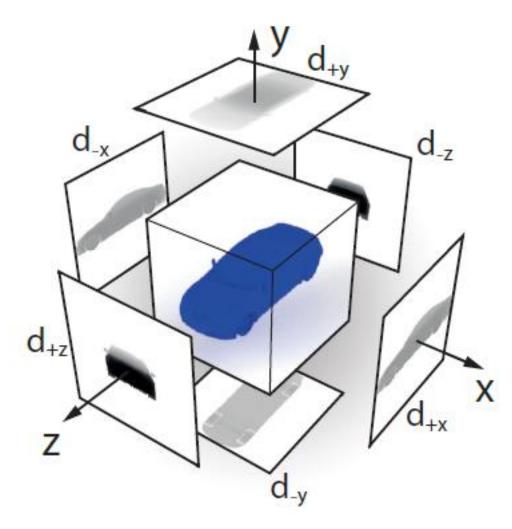
- A new architecture for dense 3D shape reconstruction at low resolutions Voxel tube network
- A proposal for high resolution 3D shape reconstruction through nested shape layers - Matryoshka Network
- Evaluation on **ShapeNet-core** dataset









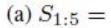


$$S = \phi(\mathbf{d}) \equiv S_x \cap S_y \cap S_z \quad \text{with} \quad \phi : \mathcal{D} \to \mathcal{S}.$$











 $(((S_1)^2)^2)^2$



 $\setminus S_2)$



 $\cup S_3$)



 $\backslash S_4)$



 $\cup S_5$.

$$S_1 \equiv \phi(\mathbf{d}_1)$$

$$S_{1:2n} \equiv S_{1:2n-1} \setminus \phi(\mathbf{d}_{2n})$$

$$S_{1:2n+1} \equiv S_{1:2n} \cup \phi(\mathbf{d}_{2n+1})$$



(b) Matryoshka doll



Method	airplane	bench	cabinet	car	cellphone	chair	conch	firearm	lamp	monitor	speaker	table	watercraft	all
3D-R2N2 [5]	51.3	42.1	71.6	79.8	66.1	46.6	62.8	54.4	38.1	46.8	66.2	51.3	51.3	56.0
OGN [27]	58.7	48.1	72.9	81.6	70.2	48.3	64.6	59.3	39.8	50.2	63.7	53.6	63.2	59.6
PSGN [8]	60.1	55.0	77.1	83.1	74.9	54.4	70.8	60.4	46.2	55.2	73.7	60.6	61.1	64.0
Ours (voxel tube network) Ours (Matryoshka network)	67.1 64.7				74.2 75.6						68.1 70.1			64.1 63.5

Method	Category	32^{3}	64^{3}	128^{3}	256^{3}
OGN [27]	car	64.1	77.1	78.2	76.6
Ours (Matryoshka)	car airplane table		48.8		79.6 59.6 41.3























Thank you for your attention

Matryoshka Networks: Predicting 3D Geometry via Nested Shape Layers

Stephan R. Richter, Stefan Roth

Andrea Felicetti, Stefano Pini, Muhammad Shahid, Raffaele Vaira